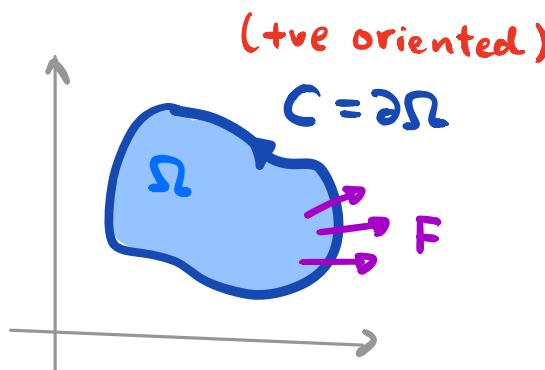


MATH 2028 Stokes and Divergence Theorem in \mathbb{R}^3

Goal: Statements of Stokes and Divergence Theorems and their applications.

Recall: Green's Theorem in \mathbb{R}^2


$$\int_C \mathbf{F} \cdot d\vec{r} = \iint_{\Omega} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

where $\mathbf{F} = (P, Q)$.

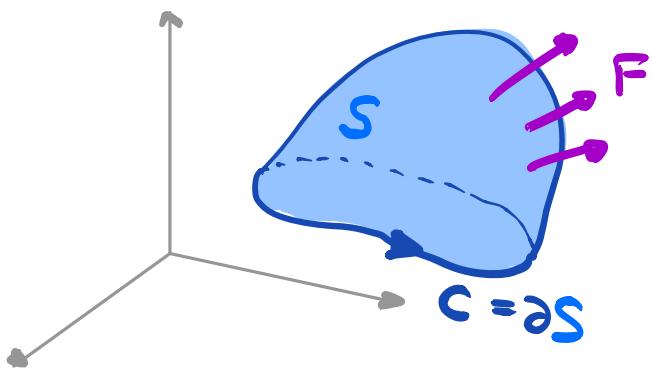
Q: Is there a similar theorem in \mathbb{R}^3 ?

A: Yes!

Stokes' Theorem

Let $S \subseteq \mathbb{R}^3$ be a surface with boundary $C = \partial S$ which is "positively" oriented (i.e. S lies on the left of C). Then, for any C' vector field \mathbf{F} defined in an open set of \mathbb{R}^3 containing $S \cup C$, we have

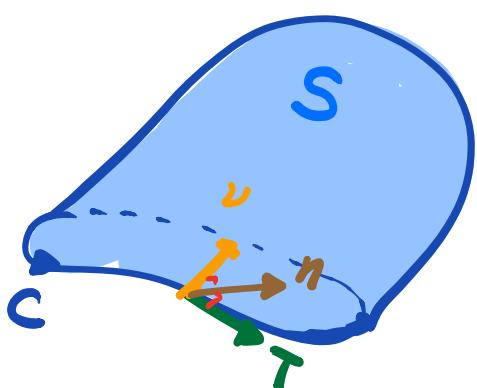
$$\int_C \mathbf{F} \cdot d\vec{r} = \iint_S \operatorname{curl} \mathbf{F} \cdot \hat{n} d\sigma$$



Remark: (1) ∂S may consist of more than one boundary curves.

E.g.) $\partial S = C_1 \cup C_2$

(2) The orientations of C and S are "compatible" in the sense that $\{T, v, n\}$ forms a "standard" orthonormal basis of \mathbb{R}^3 satisfying the "right-hand rule":



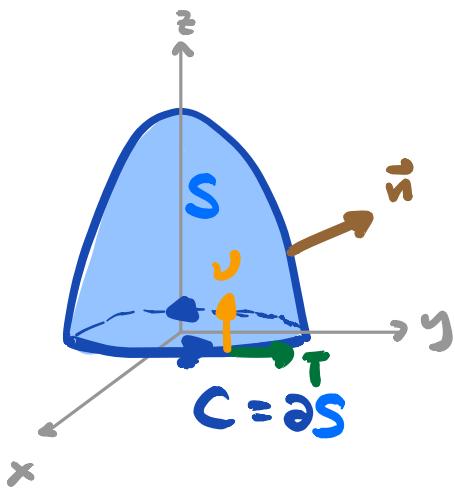
T : tangent to C

v : tangent to S but normal to C and points into S

n : normal to S

Example 1 : Compute $\iint_S \text{curl } \mathbf{F} \cdot \hat{n} d\sigma$ for
 the vector field $\mathbf{F}(x, y, z) = (z-y, x+z, -(x+y))$
 and the surface S given by the paraboloid
 $z = 4 - x^2 - y^2$ with $0 \leq z \leq 4$.

Solution:



Method 1 : Direct calculation.

Parametrize S by

$$\mathbf{g}(u, v) = (u, v, 4 - u^2 - v^2)$$

$$\text{where } u^2 + v^2 \leq 4$$

$$\frac{\partial \mathbf{g}}{\partial u} = (1, 0, -2u)$$

$$\frac{\partial \mathbf{g}}{\partial v} = (0, 1, -2v)$$

$$\frac{\partial \mathbf{g}}{\partial u} \times \frac{\partial \mathbf{g}}{\partial v} = (2u, 2v, 1) \quad \begin{matrix} \text{points upward} \\ \text{and outward!} \end{matrix}$$

On the other hand,

(correct orientation!)

$$\text{curl } \mathbf{F} = \det \begin{pmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z-y & x+z & -(x+y) \end{pmatrix} = (-2, 2, 2)$$

Therefore,

$$\begin{aligned} \iint_S \operatorname{curl} \mathbf{F} \cdot \vec{n} d\sigma &= \iint_{\{u^2+v^2 \leq 4\}} (-2, 2, 2) \cdot (2u, 2v, 1) du dv \\ &= \iint_{\{u^2+v^2 \leq 4\}} (-4u + 4v + 2) du dv \\ &= \int_0^{2\pi} \int_0^2 (-4r \cos u + 4r \sin u + 2) \cdot r dr d\theta \\ &= \int_0^{2\pi} \left(-\frac{32}{3} \cos u + \frac{32}{3} \sin u + 4 \right) d\theta \\ &= 8\pi \end{aligned}$$

Method 2 : Apply Stokes Theorem.

$$\iint_S \operatorname{curl} \mathbf{F} \cdot \vec{n} d\sigma = \int_C \mathbf{F} \cdot d\vec{r}$$

Parametrize C (with correct orientation!)

by $\gamma(t) = (2 \cos t, 2 \sin t, 0)$

where $0 \leq t \leq 2\pi$

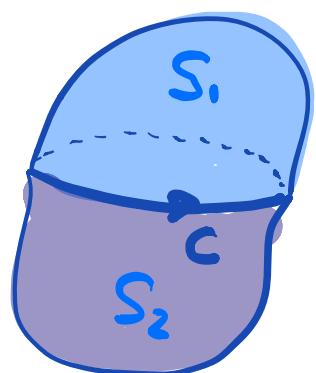
Then. $\gamma'(t) = (-2\sin t, 2\cos t, 0)$

$$F \circ \gamma(t) = (-2\sin t, 2\cos t, -2\cos t - 2\sin t)$$

$$\begin{aligned} \Rightarrow \int_C F \cdot d\vec{r} &= \int_0^{2\pi} F \circ \gamma(t) \cdot \gamma'(t) dt \\ &= \int_0^{2\pi} 4\sin^2 t + 4\cos^2 t dt \\ &= 8\pi * \quad (\text{SAME answer!}) \end{aligned}$$

Suppose two surfaces S_1, S_2 in \mathbb{R}^3 are bounded by the same curve C and lie on "opposite" sides of C . THEN: by Stokes Theorem:

$$\int_{\partial S_1} F \cdot d\vec{r} = \iint_{S_1} \text{curl } F \cdot \hat{n} d\sigma = - \iint_{S_2} \text{curl } F \cdot \hat{n} d\sigma = - \int_{\partial S_2} F \cdot d\vec{r}$$

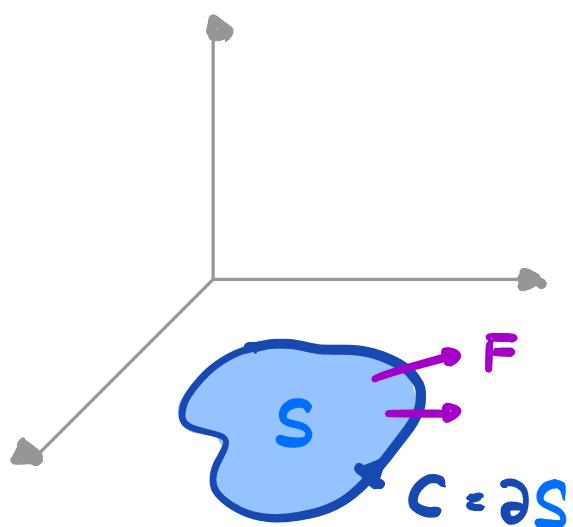


Since $\partial S_1 = C$
and $\partial S_2 = -C$

Note that Green's Theorem can be regarded as a special case of Stokes' Theorem by viewing the plane \mathbb{R}^2 as the xy-plane in \mathbb{R}^3 :

$$S \subseteq \mathbb{R}^2 = \{z=0\}$$

$$\vec{F}(x, y, z) = (P(x, y), Q(x, y), 0)$$



$$\text{curl } \vec{F} = \det \begin{pmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P(x, y) & Q(x, y) & 0 \end{pmatrix}$$

$$= (0, 0, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y})$$

Note that $\vec{n} = (0, 0, 1)$ is the corrected unit normal to S . Hence, by Stokes' Theorem

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot \vec{n} \, d\sigma$$

$$= \iint_S \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \, dA$$

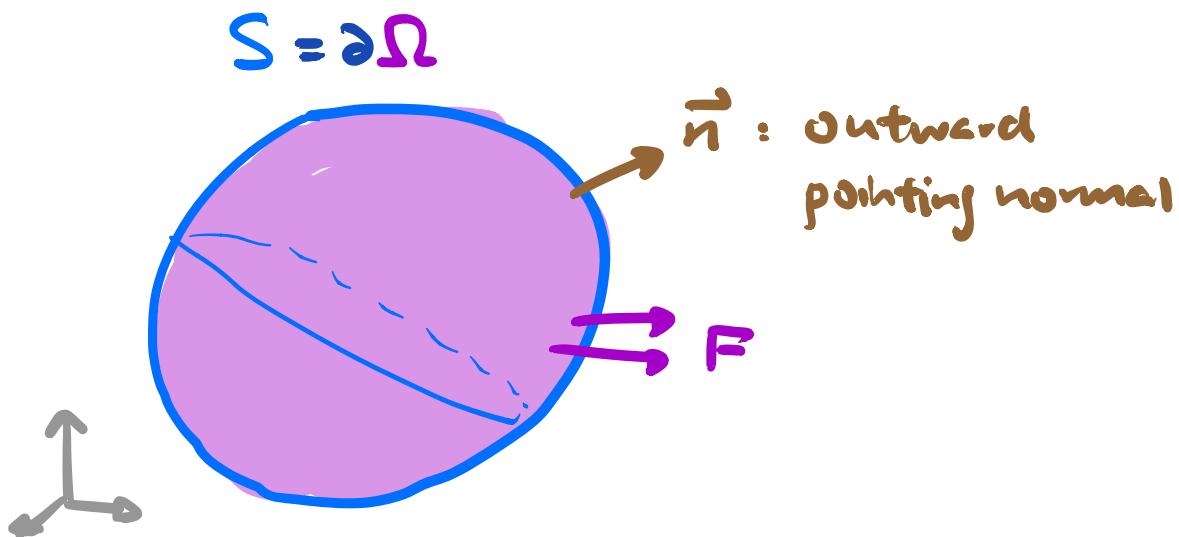
which is exactly Green's Theorem!

Now, we look at another "fundamental theorem" of calculus in \mathbb{R}^3 .

Divergence Theorem

Let $\Omega \subseteq \mathbb{R}^3$ be an open set bounded by a closed surface $S = \partial\Omega$, oriented by the unit normal \vec{n} pointing out of Ω . THEN: for any C' vector field \mathbf{F} defined on an open set containing $\bar{\Omega}$, we have

$$\iint_S \mathbf{F} \cdot \vec{n} \, d\sigma = \iiint_{\Omega} \operatorname{div} \mathbf{F} \cdot dV$$



Remark: (1) The theorem still holds when $S = \partial\Omega$ is only piecewise smooth (e.g. $\Omega = \text{cube}$)

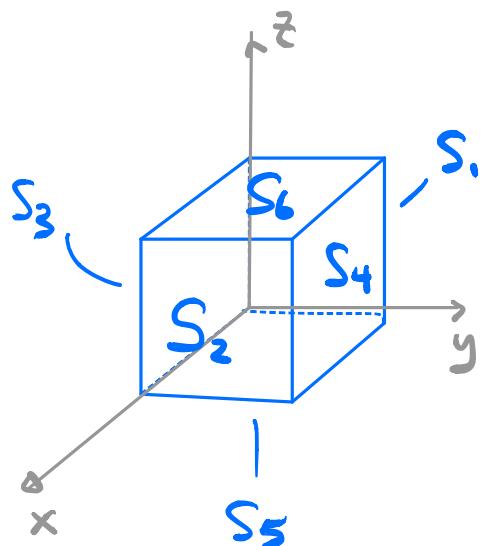
(2) There is a version of Divergence Theorem in \mathbb{R}^2 (in fact, in \mathbb{R}^n).

Example 2: Compute the flux $\iint_S \mathbf{F} \cdot \hat{\mathbf{n}} d\sigma$

for the vector field $\mathbf{F}(x, y, z) = (x^2, y^2, z^2)$

and the unit cube $S = [0, 1] \times [0, 1] \times [0, 1]$, oriented by the outward pointing normal.

Solution: Method 1 : Direct computation



Write S as the union of 6 flat pieces and compute the flux over each piece.

On S_1 $x=0, 0 \leq y, z \leq 1$

$$\vec{n} = (-1, 0, 0) \quad \text{pointing out of cube}$$

$$\mathbf{F} \cdot \vec{n} = -x^2$$

Therefore, $\iint_{S_1} \mathbf{F} \cdot \vec{n} d\sigma = \iint_{S_1} (-x^2) d\sigma = 0$

On S_2 , $x=1, 0 \leq y, z \leq 1$

$$\vec{n} = (1, 0, 0) \quad \text{pointing out of cube}$$

$$\mathbf{F} \cdot \vec{n} = x^2$$

Therefore, $\iint_{S_2} \mathbf{F} \cdot \vec{n} d\sigma = \iint_{S_2} x^2 d\sigma = 1$

Similarly, we can compute

$$\iint_{S_3} \mathbf{F} \cdot \vec{n} d\sigma = \iint_{S_5} \mathbf{F} \cdot \vec{n} d\sigma = 0$$

$$\iint_{S_4} \mathbf{F} \cdot \vec{n} d\sigma = \iint_{S_6} \mathbf{F} \cdot \vec{n} d\sigma = 1$$

Hence, the total flux $\iint_S \mathbf{F} \cdot \vec{n} d\sigma = 3$ *

Method 2 : Apply Divergence Theorem.

$$\operatorname{div} \mathbf{F} = \frac{\partial}{\partial x}(x^2) + \frac{\partial}{\partial y}(y^2) + \frac{\partial}{\partial z}(z^2) = 2(x+y+z)$$

$$\begin{aligned}\iint_S \mathbf{F} \cdot \hat{\mathbf{n}} d\sigma &= \iiint_{\Omega} \operatorname{div} \mathbf{F} dV \\&= \int_0^1 \int_0^1 \int_0^1 2(x+y+z) dx dy dz \\&= 3 *\end{aligned}$$

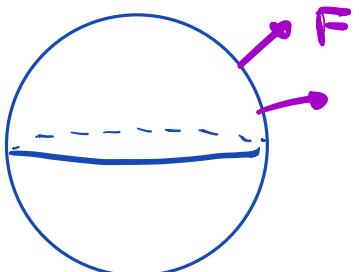
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Example 3: Compute the flux of the vector field

$\mathbf{F} = (x, y, z)$ over the sphere S of radius $a > 0$ centered at the origin, oriented by outward unit normal $\hat{\mathbf{n}}$.

Solution: $\hat{\mathbf{n}} = \frac{1}{a}(x, y, z)$

$$\iint_S \mathbf{F} \cdot \hat{\mathbf{n}} d\sigma = \iint_S a d\sigma = 4\pi a^3 *$$



$$S: x^2 + y^2 + z^2 = a^2$$